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For inductors and capacitors $i = C \frac{dv}{dt}$ and $v = L \frac{di}{dt}$ so we need to differentiate i(t) and v(t) when analysing circuits containing them.

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$$v(t) = \sin t \Rightarrow \frac{dv}{dt} = \cos t$$

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 $\sin 2\pi ft$ makes f complete repetitions every time t increases by 1; this gives a *frequency* of f cycles per second, or f Hz.

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 $(1) = \begin{pmatrix} 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 2 & 3 & 4 \\ 1 & 1 & 1 & 2 & 3 & 4 \\ 1 & 1 & 1 & 2 & 3 & 1 \\ 1 & 1 & 1 & 2 & 3 & 1 \\ 1 & 1 & 1 & 2 & 3 & 1 \\ 1 & 1 & 1 & 2 & 3 & 1 \\ 1 &$



 $\sin 2\pi ft$ makes f complete repetitions every time t increases by 1; this gives a *frequency* of f cycles per second, or f Hz. We often use the *angular frequency*, $\omega = 2\pi f$ instead. ω is measured in radians per second. E.g. 50 Hz $\simeq 314$ rad.s⁻¹.

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A useful way to think of a cosine wave is as the projection of a rotating rod onto the horizontal axis.

For a unit-length rod, the projection has length $\cos \theta$.



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- For a unit-length rod, the projection has length $\cos \theta$.
- If the rod is rotating at a speed of f revolutions per second, then θ increases uniformly with time: $\theta = 2\pi f t$.



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The only difference between \cos and \sin is the starting position of the rod:



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 $v = \cos 2\pi f t$

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 $v = \cos 2\pi f t \qquad \qquad v = \sin 2\pi f t$

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 $v = \cos 2\pi f t$

 $v = \sin 2\pi ft = \cos\left(2\pi ft - \frac{\pi}{2}\right)$

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The only difference between \cos and \sin is the starting position of the rod:



 $v = \cos 2\pi ft \qquad \qquad v = \sin 2\pi ft = \cos \left(2\pi ft - \frac{\pi}{2}\right)$

 $\sin 2\pi ft \log \cos 2\pi ft$ by 90° (or $\frac{\pi}{2}$ radians) because its peaks occurs $\frac{1}{4}$ of a cycle later (equivalently $\cos \text{leads } \sin$).

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If the rod has length A and starts at an angle ϕ then the projection onto the horizontal axis is

$$A\cos\left(2\pi ft + \phi\right)$$



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- $A\cos(2\pi ft + \phi) = A\cos\phi\cos 2\pi ft A\sin\phi\sin 2\pi ft$
 - $= X\cos 2\pi ft Y\sin 2\pi ft$



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If the rod has length A and starts at an angle ϕ then the projection onto the horizontal axis is

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 $A\cos\left(2\pi ft + \phi\right)$ = $A\cos\phi\cos2\pi ft - A\sin\phi\sin2\pi ft$

At time t = 0, the tip of the rod has coordinates





 $(X, Y) = (A \cos \phi, A \sin \phi).$ If we think of the plane as an Argand Diagram (or complex plane), then the complex number X + jY corresponding to the tip of the rod at t = 0 is called a *phasor*.

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The *magnitude* of the phasor, $A = \sqrt{X^2 + Y^2}$, gives the amplitude (peak value) of the sine wave.

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 $A\cos\left(2\pi ft + \phi\right)$ = $A\cos\phi\cos2\pi ft - A\sin\phi\sin2\pi ft$

$$= X\cos 2\pi ft - Y\sin 2\pi ft$$

Y- A Ø X

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The *magnitude* of the phasor, $A = \sqrt{X^2 + Y^2}$, gives the amplitude (peak value) of the sine wave.

The *argument* of the phasor, $\phi = \arctan \frac{Y}{X}$, gives the phase shift relative to $\cos 2\pi ft$.

If $\phi > 0$, it is *leading* and if $\phi < 0$, it is *lagging* relative to $\cos 2\pi f t$.

 $V = 1, f = 50 \, \text{Hz}$

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- V = -j $v(t) = \sin 2\pi f t$
 - V = -1 0.5j



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V = -j $v(t) = \sin 2\pi f t$

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$$V = 1, f = 50 \text{ Hz}$$
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$$V = X + jY$$



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Phasors: 10 - 5 / 11

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 $V = A \angle \phi = A e^{j\phi}$ $v(t) = A \cos \left(2\pi f t + \phi\right)$

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Casio: $\operatorname{Pol}(X, Y) \to A, \phi, \operatorname{Rec}(A, \phi) \to X, Y$. Saved $\to X \& Y$ mems.

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Phasors

V=P+jQ

Waveforms

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 $a \times v(t)$

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Phasors

V = P + jQ

Waveforms

 $v(t) = P \cos \omega t - Q \sin \omega t$ where $\omega = 2\pi f$.

 $a \times v(t) = aP\cos\omega t - aQ\sin\omega t$

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 $V_1 + V_2$

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Adding or scaling is the same for waveforms and phasors.

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Adding or scaling is the same for waveforms and phasors.

 $\frac{dv}{dt} = -\omega P \sin \omega t - \omega Q \cos \omega t$ $= (-\omega Q) \cos \omega t - (\omega P) \sin \omega t$

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 $a \times v(t) = aP \cos \omega t - aQ \sin \omega t$ $v_1(t) + v_2(t)$

Adding or scaling is the same for waveforms and phasors.

$$\dot{V} = (-\omega Q) + j(\omega P) \qquad \qquad \frac{\omega \sigma}{dt} = -\omega P \sin \omega t - \omega Q \cos \omega t \\ = (-\omega Q) \cos \omega t - (\omega P) \sin \omega t$$

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 $a \times v(t) = aP \cos \omega t - aQ \sin \omega t$ $v_1(t) + v_2(t)$

Adding or scaling is the same for waveforms and phasors.

$$\dot{V} = (-\omega Q) + j (\omega P)$$
$$= j\omega (P + jQ)$$

 $\frac{dv}{dt} = -\omega P \sin \omega t - \omega Q \cos \omega t$ $= (-\omega Q) \cos \omega t - (\omega P) \sin \omega t$

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Adding or scaling is the same for waveforms and phasors.

$$\dot{V} = (-\omega Q) + j (\omega P)$$

= $j\omega (P + jQ)$
= $j\omega V$

$$\frac{dv}{dt} = -\omega P \sin \omega t - \omega Q \cos \omega t$$
$$= (-\omega Q) \cos \omega t - (\omega P) \sin \omega t$$

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Adding or scaling is the same for waveforms and phasors.

 $\frac{dv}{dt} = -\omega P \sin \omega t - \omega Q \cos \omega t$ $= (-\omega Q) \cos \omega t - (\omega P) \sin \omega t$

Differentiating waveforms corresponds to multiplying phasors by $j\omega$.

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Waveforms

 $v(t) = P \cos \omega t - Q \sin \omega t$ where $\omega = 2\pi f$.

 $a \times v(t) = aP \cos \omega t - aQ \sin \omega t$ $v_1(t) + v_2(t)$

Adding or scaling is the same for waveforms and phasors.

 $\dot{V} = (-\omega Q) + j(\omega P)$ = $j\omega (P + jQ)$ = $j\omega V$ $\frac{dv}{dt} = -\omega P \sin \omega t - \omega Q \cos \omega t$ = $(-\omega Q) \cos \omega t - (\omega P) \sin \omega t$

Differentiating waveforms corresponds to multiplying phasors by $j\omega.$

Rotate anti-clockwise 90° and scale by $\omega = 2\pi f$.



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Resistor:

$$v(t) = Ri(t)$$



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Resistor:

$$v(t) = Ri(t) \Rightarrow V = RI$$



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$$v(t) = Ri(t) \Rightarrow V = RI \Rightarrow \frac{V}{I} = R$$



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Resistor:

$$v(t) = Ri(t) \Rightarrow V = RI \quad \Rightarrow \frac{V}{I} = R$$





 $v(t) = L\frac{di}{dt}$



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Resistor:

$$v(t) = Ri(t) \Rightarrow V = RI \quad \Rightarrow \frac{V}{I} = R$$

Inductor:

$$v(t) = L\frac{di}{dt} \Rightarrow V = j\omega LI$$





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Resistor:

$$v(t) = Ri(t) \Rightarrow V = RI \quad \Rightarrow \frac{V}{I} = R$$



$$v(t) = L \frac{di}{dt} \Rightarrow V = j\omega LI \quad \Rightarrow \frac{V}{I} = j\omega L$$





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Resistor:

$$v(t) = Ri(t) \Rightarrow V = RI \quad \Rightarrow \frac{V}{I} = R$$

Inductor:

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Capacitor:

$$i(t) = C \frac{dv}{dt}$$

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Resistor:

$$v(t) = Ri(t) \Rightarrow V = RI \quad \Rightarrow \frac{V}{I} = R$$

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Capacitor:

$$i(t) = C \frac{dv}{dt} \Rightarrow I = j\omega CV$$







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Resistor:

$$v(t) = Ri(t) \Rightarrow V = RI \quad \Rightarrow \frac{V}{I} = R$$



$$v(t) = L \frac{di}{dt} \Rightarrow V = j\omega LI \quad \Rightarrow \frac{V}{I} = j\omega L$$



$$i(t) = C \frac{dv}{dt} \Rightarrow I = j\omega CV \Rightarrow \frac{V}{I} = \frac{1}{j\omega C}$$







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Resistor:

$$v(t) = Ri(t) \Rightarrow V = RI \quad \Rightarrow \frac{V}{I} = R$$

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Capacitor:

$$i(t) = C \frac{dv}{dt} \Rightarrow I = j\omega CV \Rightarrow \frac{V}{I}$$



For all three components, phasors obey Ohm's law if we use the *complex impedances* $j\omega L$ and $\frac{1}{j\omega C}$ as the "resistance" of an inductor or capacitor.

 $\frac{1}{j\omega C}$

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Complex Impedances

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For all three components, phasors obey Ohm's law if we use the *complex impedances* $j\omega L$ and $\frac{1}{j\omega C}$ as the "resistance" of an inductor or capacitor.

If all sources in a circuit are sine waves having the same frequency, we can do circuit analysis exactly as before by using complex impedances.

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Given $v = 10 \sin \omega t$ where $\omega = 2\pi \times 1000$, find $v_C(t)$.



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 v_C

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Given $v = 10 \sin \omega t$ where $\omega = 2\pi \times 1000$, find $v_C(t)$.

(1) Find capacitor complex impedance $Z = \frac{1}{j\omega C} = \frac{1}{6.28j \times 10^{-4}} = -1592j$





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- (1) Find capacitor complex impedance $Z = \frac{1}{j\omega C} = \frac{1}{6.28j \times 10^{-4}} = -1592j$
 - (2) Solve circuit with phasors $V_C = V \times \frac{Z}{R+Z}$





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Phasor Analysis

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(1) Find capacitor complex impedance $Z = \frac{1}{j\omega C} = \frac{1}{6.28j \times 10^{-4}} = -1592j$

(2) Solve circuit with phasors $V_C = V \times \frac{Z}{R+Z}$ $= -10j \times \frac{-1592j}{1000-1592j}$ $= -4.5 - 7.2j = 8.47\angle -122^{\circ}$ $v_C = 8.47\cos(\omega t - 122^{\circ})$







Phasor Analysis

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Phasors add like vectors







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Capacitors: $i = C \frac{dv}{dt} \Rightarrow I$ leads VInductors: $v = L \frac{di}{dt} \Rightarrow V$ leads I

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COMPLEX ARITHMETIC TRICKS:

(1) $j \times j = -j \times -j = -1$

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(1)
$$j \times j = -j \times -j = -1$$

(2) $\frac{1}{j} = -j$
(3) $a + jb = r \angle \theta = re^{j\theta}$
where $r = \sqrt{a^2 + b^2}$ and $\theta = \arctan \frac{b}{a}$ (±180° if $a < 0$)

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where $r = \sqrt{a^2 + b^2}$ and $\theta = \arctan \frac{b}{a}$ (±180° if $a < 0$)
(4) $r \angle \theta = re^{j\theta} = (r \cos \theta) + j (r \sin \theta)$

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(3) $a + jb = r \angle \theta = re^{j\theta}$
where $r = \sqrt{a^2 + b^2}$ and $\theta = \arctan \frac{b}{a}$ (±180° if $a < 0$)
(4) $r \angle \theta = re^{j\theta} = (r \cos \theta) + j (r \sin \theta)$
(5) $a \angle \theta \times b \angle \phi = ab \angle (\theta + \phi)$ and $\frac{a \angle \theta}{b \angle \phi} = \frac{a}{b} \angle (\theta - \phi)$.
Multiplication and division are much easier in polar form.

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Capacitors: $i = C \frac{dv}{dt} \Rightarrow I$ leads VInductors: $v = L \frac{di}{dt} \Rightarrow V$ leads I

Mnemonic: CIVIL = "In a capacitor I lead V but V leads I in an inductor".

COMPLEX ARITHMETIC TRICKS:

(1)
$$j \times j = -j \times -j = -1$$

(2) $\frac{1}{j} = -j$
(3) $a + jb = r \angle \theta = re^{j\theta}$
where $r = \sqrt{a^2 + b^2}$ and $\theta = \arctan \frac{b}{a}$ (±180° if $a < 0$)
(4) $r \angle \theta = re^{j\theta} = (r \cos \theta) + j (r \sin \theta)$
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Multiplication and division are much easier in polar form.

(6) All scientific calculators will convert rectangular to/from polar form.

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COMPLEX ARITHMETIC TRICKS:

arithmetic $(+, -, \times, \div, x^2, \frac{1}{x}, |x|, x^*)$ in CMPLX mode.

Learn how to use this: it will save lots of time and errors.

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For any network (resistors+capacitors+inductors):

```
(1) Impedance = Resistance + j \times Reactance
```

```
Z = R + jX (\Omega)
```

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For any network (resistors+capacitors+inductors):

(1) Impedance = Resistance + $j \times$ Reactance

 $Z = R + jX (\Omega)$ $|Z|^2 = R^2 + X^2 \qquad \angle Z = \arctan \frac{X}{R}$

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Note:

 $Y = G + jB = \frac{1}{Z}$

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So $G = \frac{R}{R^2 + X^2} = \frac{R}{|Z|^2}$
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<u>Beware:</u> $G \neq \frac{1}{R}$ unless X = 0.

Phasors: 10 - 10 / 11

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• Sine waves are the only bounded signals whose shape is unchanged by differentiation.

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- Sine waves are the only bounded signals whose shape is unchanged by differentiation.
- Think of a sine wave as the projection of a rotating rod onto the horizontal (or real) axis.
 - A *phasor* is a complex number representing the length and position of the rod at time t = 0.

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• If
$$V = a + jb = r \angle \theta = re^{j\theta}$$
, then
 $v(t) = a \cos \omega t - b \sin \omega t = r \cos (\omega t + \theta) = \Re \left(Ve^{j\omega t} \right)$

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- If all sources in a linear circuit are sine waves having the same frequency, we can use phasors for circuit analysis:

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See Hayt Ch 10 or Irwin Ch 8